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$c t d x(t)$ Thus, if the

input $x(t)$ is bounded,

then the output $y(t)$ is

also bounded and the

system is BIBO stable.

3. Evaluate $y(t) x(t)$

$h(t)$, where $x(t) u(t) u(t$

3) and $h(t) u(t) u(t 2)$

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