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Root Locus Method -
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~~Learning Problem 1 on Block~~

~~Diagram Reduction~~ **Block**

Diagram Reduction Audio

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~~with different amplitude,~~

~~phase shift in phased array~~

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Reference Handbook

Understanding PID Control,

Part 1: What is PID Control?

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Chaparro-Akan – Signals and
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0.6 Differential and
difference equations – Find
the ordinary differential
equation relating a current
source $i_s(t) = \cos(0t)$ with
the current $i_L(t)$ in an
inductor, with inductance $L =$
1 Henry, connected in
parallel with a resistor of
 $R = 1$ (see Fig. 3).

Solution Manual for
Additional Problems for
SIGNALS AND ...

Chaparro – Signals and
Systems using MATLAB 0.9 0.9
(a) If $w = e^z$ then $\log(w) = z =$
 $1 + j1$ given that the log
and exp functions are the

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inverse of each other. The
real and imaginary of w are
 $w = e^{j1} = \cos(1) + j\sin(1)$
| {z
} real part + j {z
} imaginary part (b) The
imaginary parts are
cancelled and the real parts
added twice in $w + w^* = 2\text{Re}[w]$
 $= 2\cos(1)$

Signals and Systems using
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Chaparro-Akan – Signals and
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Use Euler's identity to

(a) show the identities (i)
 $\cos(\theta + \phi) = \cos(\theta)\cos(\phi) - \sin(\theta)\sin(\phi)$
(ii) $\sin(\theta + \phi) = \sin(\theta)\cos(\phi) + \cos(\theta)\sin(\phi)$;

(b) find an expression for
 $\cos(\theta)\cos(\phi)$, and for $\sin(\theta)\sin(\phi)$

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Solution Manual:
$$e^{j\theta} e^{j\phi} = \cos(\theta + \phi) + j\sin(\theta + \phi) = [\cos(\theta)\cos(\phi) - \sin(\theta)\sin(\phi)] + j[\sin(\theta)\cos(\phi) + \cos(\theta)\sin(\phi)].$$

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Systems using MATLAB. 2.10.
2.10 The input to all the
systems is $x(t) = \cos(t)$,

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?? < t < ? (a) The system is non-linear, as the output $y(t) = \cos^2(t) = 0.5(1 + \dots$

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(a) Yes, expressing $e^{j2t} = \cos(2t) + j\sin(2t)$,

periodic of fundamental

period $T_0 = 1$, then the

integral is the area [MOBI]

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