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~~ce-1 = 2t y', We get y' = (1 + t)y t2 2. </J (t, y, y') = ty' - 2y - t2 must be solved for y'. We get f 2y + t2 y=--. t 5.~~

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Hence, the velocity is $v(t) = -gt + v_0 = -32t + 20$, and the first equation in (3.15) becomes $dx = -gt + v_0 = -32t + 20. dt$

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Solving by integration, we get $x(t) = -gt^2 + v_0 t + C_2 = -16t^2 + 20t + C_2$. Once more we evaluate this at $t = 0$ to show that $C_2 = x(0) = x_0 = 6$, the initial elevation of the ball.

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The MATLAB function `dfield5` is used to plot solutions of first order differential equations of the form $y' = f(t, y)$ using a variety of solvers: Euler, RK2, RK4, and Dormand-Prince. Direction fields can also be drawn. The MATLAB function `pplane5` is used to draw solutions of planar, autonomous systems having the form $x' = f(x, y)$, $y' = g(x, y)$.

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